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A Kenmotsu metric as a conformal η -Einstein soliton

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The object of the present paper is to study some properties of Kenmotsu manifold whose metric is conformal η -Einstein soliton. We have studied certain properties of Kenmotsu manifold admitting conformal η -Einstein soliton. We have also constructed a 3-dimensional Kenmotsu manifold satisfying conformal η -Einstein soliton.

 $\it Key\ words\ and\ phrases:\ Einstein\ soliton,\ η-Einstein\ soliton,\ conformal\ η-Einstein\ soliton,\ η-Einstein\ manifold,\ Kenmotsu\ manifold.$

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Introduction

The notion of Einstein soliton was introduced by G. Catino and L. Mazzieri [3] in 2016, which generates self-similar solutions to Einstein flow

$$\frac{\partial g}{\partial t} = -2\left(S - \frac{r}{2}g\right),\,$$

where *S* is Ricci tensor, *g* is Riemannian metric and *r* is the scalar curvature.

The equation of the η -Einstein soliton [2] is given by,

$$\pounds_{\xi}g + 2S + (2\lambda - r)g + 2\mu\eta \otimes \eta = 0,$$

where \mathcal{L}_{ξ} is the Lie derivative along the vector field ξ , S is the Ricci tensor, r is the scalar curvature of the Riemannian metric g, and λ and μ are real constants. For $\mu = 0$, the data (g, ξ, λ) is called Einstein soliton.

In 2018, M.D. Siddiqi [6] introduced the notion of conformal η -Ricci soliton [8] as

$$\pounds_{\xi}g + 2S + \left[2\lambda - \left(p + \frac{2}{n}\right)\right]g + 2\mu\eta \otimes \eta = 0,$$

where \mathcal{L}_{ξ} is the Lie derivative along the vector field ξ , S is the Ricci tensor, λ , μ are constants, p is a scalar non-dynamical field (time dependent scalar field) and n is the dimension of manifold. For $\mu = 0$, conformal η -Ricci soliton becomes conformal Ricci soliton [7].

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In [9], S. Roy, S. Dey and A. Bhattacharyya have defined conformal Einstein soliton, which can be written as

$$\pounds_{V}g + 2S + \left[2\lambda - r + \left(p + \frac{2}{n}\right)\right]g = 0,\tag{1}$$

where \mathcal{L}_V is the Lie derivative along the vector field V, S is the Ricci tensor, r is the scalar curvature of the Riemannian metric g, λ is real constant, p is a scalar non-dynamical field (time dependent scalar field) and n is the dimension of manifold.

So we introduce the notion of conformal η -Einstein soliton as follows.

Definition 1. A Riemannian manifold (M,g) of dimension n is said to admit conformal η -Einstein soliton if

$$\pounds_{\xi}g + 2S + \left[2\lambda - r + \left(p + \frac{2}{n}\right)\right]g + 2\mu\eta \otimes \eta = 0,\tag{2}$$

where \mathcal{L}_{ξ} is the Lie derivative along the vector field ξ , λ , μ are real contants and S, r, p, n are same as defined in (1).

In the present paper, we study conformal η -Einstein soliton on Kenmotsu manifold. The paper is organized as follows.

After introduction, section 2 is devoted for preliminaries on (2n+1)-dimensional Kenmotsu manifold. In section 3, we have studied conformal η -Einstein soliton on Kenmotsu manifold. Here we proved that if a (2n+1)-dimensional Kenmotsu manifold admits conformal η -Einstein soliton then the manifold becomes η -Einstein. We have also characterized the nature of the manifold if the manifold is Ricci symmetric and the Ricci tensor is η -recurrent. Also we have discussed the condition, when the manifold has cyclic Ricci tensor. Then we have obtained the conditions in a (2n+1)-dimensional Kenmotsu manifold admitting conformal η -Einstein soliton, when a vector field V is pointwise co-linear with ξ and a (0,2)-tensor field h is parallel with respect to the Levi-Civita connection associated to g. We have also examined the nature of a Ricci-recurrent Kenmotsu manifold admitting conformal η -Einstein soliton.

In last section, we have given an example of a 3-dimensional Kenmotsu manifold satisfying conformal η -Einstein soliton.

1 Preliminaries

Let M be a (2n+1)-dimensional connected almost contact metric manifold with an almost contact metric structure (ϕ, ξ, η, g) , where ϕ is a (1,1)-tensor field, ξ is a vector field, η is a 1-form and g is the compatible Riemannian metric such that

$$\phi^2(X) = -X + \eta(X)\xi, \ \eta(\xi) = 1, \ \eta \circ \phi = 0, \ \phi\xi = 0,$$
 (3)

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \tag{4}$$

$$g(X, \phi Y) = -g(\phi X, Y),$$

$$g(X,\xi) = \eta(X),\tag{5}$$

for all vector fields $X, Y \in \chi(M)$.

The fundamental 2-form Φ on an almost contact metric manifold M^{2n+1} is defined by $\Phi(X,Y)=g(X,\phi Y)$ for any vector fields X and Y on M^{2n+1} . In an almost contact metric manifold, we have $\eta \wedge \Phi^n \neq 0$.

When $\Phi = d\eta$, an almost contact metric manifold becomes contact metric manifold.

An almost contact metric manifold satisfying $d\eta=0$ and $d\Phi=2\eta\wedge\Phi$ is said to be an almost Kenmotsu manifold [4].

An almost contact metric manifold is said to be a Kenmotsu manifold [5] if

$$(\nabla_X \phi) Y = -g(X, \phi Y) \xi - \eta(Y) \phi X,$$

$$\nabla_X \xi = X - \eta(X) \xi,$$
(6)

where ∇ denotes the Riemannian connection of g.

In a Kenmotsu manifold the following relations hold [1]:

$$\eta(R(X,Y)Z) = g(X,Z)\eta(Y) - g(Y,Z)\eta(X),$$

$$R(X,Y)\xi = \eta(X)Y - \eta(Y)X,$$

$$R(X,\xi)Y = g(X,Y)\xi - \eta(Y)X,$$
(7)

where *R* is the Riemannian curvature tensor,

$$S(X,\xi) = -2n\eta(X),\tag{8}$$

$$S(\phi X, \phi Y) = S(X, Y) + 2n\eta(X)\eta(Y),$$

$$(\nabla_X \eta)Y = g(X, Y) - \eta(X)\eta(Y),$$
(9)

for all vector fields $X, Y, Z \in \chi(M)$.

Now we know,

$$(\pounds_{\xi}g)(X,Y) = g(\nabla_X\xi,Y) + g(X,\nabla_Y\xi),\tag{10}$$

for all vector fields $X, Y \in \chi(M)$. Then using (6) and (10), we get,

$$(\pounds_{\tilde{c}}g)(X,Y) = 2[g(X,Y) - \eta(X)\eta(Y)]. \tag{11}$$

2 Conformal η-Einstein soliton on Kenmotsu manifold

Let M be a (2n+1)-dimensional Kenmotsu manifold. Consider the conformal η -Einstein soliton (2) on M as

$$(\pounds_{\xi}g)(X,Y) + 2S(X,Y) + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g(X,Y) + 2\mu\eta(X)\eta(Y) = 0$$

for all vector fields $X, Y \in \chi(M)$.

Theorem 1. If the metric of a (2n+1)-dimensional Kenmotsu manifold is a conformal η -Einstein soliton, then the manifold becomes η -Einstein and the scalar curvature is

$$\left(p+\frac{2}{2n+1}\right)-4n+2\lambda+2\mu.$$

Proof. First, using (11), the above equation becomes,

$$S(X,Y) = -\left[\lambda - \frac{r}{2} + \frac{\left(p + \frac{2}{2n+1}\right)}{2} + 1\right]g(X,Y) - (\mu - 1)\eta(X)\eta(Y). \tag{12}$$

Taking $Y = \xi$ in the above equation and using (8), we get,

$$r = \left(p + \frac{2}{2n+1}\right) - 4n + 2\lambda + 2\mu,\tag{13}$$

since $\eta(X) \neq 0$, for all $X \in \chi(M)$.

Also from (12), it follows that the manifold is η -Einstein and this completes the proof. \square

Theorem 2. If the metric of a (2n+1)-dimensional Ricci symmteric Kenmotsu manifold is a conformal η -Einstein soliton, then $\mu = 1$ and the scalar curvature is $\left(p + \frac{2}{2n+1}\right) - 4n + 2\lambda + 2$.

Proof. We know, that $(\nabla_X S)(Y, Z) = X(S(Y, Z)) - S(\nabla_X Y, Z) - S(Y, \nabla_X Z)$, for all vector fields X, Y, Z on M and ∇ is the Levi-Civita connection associated with g.

Now replacing the expression of S from (12), we obtain

$$(\nabla_X S)(Y, Z) = -(\mu - 1)[\eta(Z)(\nabla_X \eta)Y + \eta(Y)(\nabla_X \eta)Z] \tag{14}$$

for all vector fields X, Y, Z on M.

As the manifold M is Ricci symmetric, i.e $\nabla S = 0$.

Then from (14), we get

$$-(\mu - 1)[\eta(Z)(\nabla_X \eta)Y + \eta(Y)(\nabla_X \eta)Z] = 0$$

for all vector fields $X, Y, Z \in \chi(M)$.

Taking $Z = \xi$ in the above equation and using (9), (3), we obtain, $\mu = 1$.

Then from (13), we get

$$r = \left(p + \frac{2}{2n+1}\right) - 4n + 2\lambda + 2.$$

Hence, we complete the proof.

Theorem 3. If the metric of a (2n+1)-dimensional Kenmotsu manifold is a conformal η -Einstein soliton and the Ricci tensor S is η -recurrent, then the scalar curvature is

$$2\lambda + 2\mu + \left(p + \frac{2}{2n+1}\right).$$

Proof. If the Ricci tensor *S* is η -recurrent, then we have $\nabla S = \eta \otimes S$, which implies

$$(\nabla_X S)(Y, Z) = \eta(X)S(Y, Z)$$

for all vector fields X, Y, Z on M. Using (14), the above equation reduces to

$$-(\mu-1)[\eta(Z)(\nabla_X\eta)Y+\eta(Y)(\nabla_X\eta)Z]=\eta(X)S(Y,Z).$$

Taking $Y = \xi$, $Z = \xi$ in the above equation and using (9), (12), we get

$$\left[\lambda + \mu - \frac{r}{2} + \frac{p + \frac{2}{2n+1}}{2}\right] \eta(X) = 0,$$

which implies

$$r = 2\lambda + 2\mu + \left(p + \frac{2}{2n+1}\right).$$

This completes the proof.

Theorem 4. Let the metric of a (2n+1)-dimensional Kenmotsu manifold M is a conformal η -Einstein soliton. Then M has cyclic Ricci tensor if $\mu = 1$.

Proof. Similarly from (14), we get

$$(\nabla_{Y}S)(Z,X) = -(\mu - 1)[\eta(X)(\nabla_{Y}\eta)Z + \eta(Z)(\nabla_{X}\eta)Y],\tag{15}$$

and

$$(\nabla_Z S)(X, Y) = -(\mu - 1)[\eta(Y)(\nabla_Z \eta)X + \eta(X)(\nabla_Z \eta)Y] \tag{16}$$

for all vector fields X, Y, Z on M.

Then adding (14), (15), (16) and using (9), (4), we obtain

$$(\nabla_{X}S)(Y,Z) + (\nabla_{Y}S)(Z,X) + (\nabla_{Z}S)(X,Y) = -2(\mu - 1)[\eta(X)g(\phi Y,\phi Z) + \eta(Y)g(\phi Z,\phi X) + \eta(Z)g(\phi X,\phi Y)].$$
(17)

Now, as the manifold *M* has cyclic Ricci tensor, i.e

$$(\nabla_X S)(Y, Z) + (\nabla_Y S)(Z, X) + (\nabla_Z S)(X, Y) = 0,$$

then from (17), we have

$$(\mu - 1)[\eta(X)g(\phi Y, \phi Z) + \eta(Y)g(\phi Z, \phi X) + \eta(Z)g(\phi X, \phi Y)] = 0.$$

Taking $X = \xi$ in the above equation and using (3), we get $\mu = 1$.

Again, if we take $\mu = 1$ in (17), we obtain $(\nabla_X S)(Y, Z) + (\nabla_Y S)(Z, X) + (\nabla_Z S)(X, Y) = 0$, i.e the manifold M has cyclic Ricci tensor and this completes the proof.

Corollary 1. If a (2n+1)-dimensional Kenmotsu manifold M has a cyclic Ricci tensor and the metric is a conformal η -Einstein soliton, then the scalar curvature is $(p + \frac{2}{2n+1}) - 4n + 2\lambda + 2$.

Proof. If
$$\mu = 1$$
, then from (13) we obtain $r = \left(p + \frac{2}{2n+1}\right) - 4n + 2\lambda + 2$.

Theorem 5. Let M be a (2n+1)-dimensional Kenmotsu manifold admitting a conformal η -Einstein soliton (g, V), V being a vector field on M. If V is pointwise co-linear with ξ , a vector field on M, then V is a constant multiple of ξ , provided the scalar curvature is

$$2\lambda + 2\mu + \left(p + \frac{2}{2n+1}\right) - 4n.$$

Proof. A conformal η -Einstein soliton is defined on a (2n+1)-dimensional Kenmotsu manifold M as

$$\pounds_{V}g + 2S + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g + 2\mu\eta \otimes \eta = 0,\tag{18}$$

where \mathcal{E}_V is the Lie derivative along the vector field V, S is the Ricci tensor, r is the scalar curvature of the Riemannian metric g, λ , μ are real contants, p is a scalar non-dynamical field (time dependent scalar field).

Since, *V* is pointwise co-linear with ξ , let $V = b\xi$, where *b* is a function on *M*.

Then (18) becomes

$$(\pounds_{b\xi}g)(X,Y) + 2S(X,Y) + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g(X,Y) + 2\mu\eta(X)\eta(Y) = 0$$

for all vector fields *X*, *Y* on *M*. Applying the property of Lie derivative and Levi-Civita connection, we have

$$bg(\nabla_X \xi, Y) + (Xb)\eta(Y) + bg(\nabla_Y \xi, X) + (Yb)\eta(X) + 2S(X, Y)$$
$$+ \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g(X, Y) + 2\mu\eta(X)\eta(Y) = 0.$$

Now using (6), we get

$$\begin{aligned} 2bg(X,Y) - 2b\eta(X)\eta(Y) + (Xb)\eta(Y) + (Yb)\eta(X) + 2S(X,Y) \\ + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g(X,Y) + 2\mu\eta(X)\eta(Y) &= 0. \end{aligned}$$

Taking $Y = \xi$ in the above equation and using (3), (5), (8), we obtain

$$(Xb) + (\xi b)\eta(X) - 4n\eta(X) + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]\eta(X) + 2\mu\eta(X) = 0.$$
 (19)

Then by putting $X = \xi$, the above equation reduces to

$$\xi b = 2n + \frac{r}{2} - \lambda - \mu - \frac{\left(p + \frac{2}{2n+1}\right)}{2}.$$
 (20)

Using (20), equation (19) becomes

$$(Xb) + \left[\lambda + \mu + \frac{\left(p + \frac{2}{2n+1}\right)}{2} - 2n - \frac{r}{2}\right] \eta(X) = 0.$$
 (21)

Applying exterior differentiation in (21), we have

$$\left[\lambda + \mu + \frac{\left(p + \frac{2}{2n+1}\right)}{2} - 2n - \frac{r}{2}\right] d\eta = 0.$$
 (22)

Now we know

$$d\eta(X,Y) = \frac{1}{2} \Big[(\nabla_X \eta) Y - (\nabla_Y \eta) X \Big]$$

for all vector fields X, Y on M. Using (9), the above equation becomes $d\eta = 0$. Hence the 1-form η is closed.

So from (22), either $r=2\lambda+2\mu+\left(p+\frac{2}{2n+1}\right)-4n$ or $r\neq 2\lambda+2\mu+\left(p+\frac{2}{2n+1}\right)-4n$. If $r=2\lambda+2\mu+\left(p+\frac{2}{2n+1}\right)-4n$, (21) reduces to (Xb)=0. This implies that b is constant and this completes the proof.

Theorem 6. In a (2n+1)-dimensional Kenmotsu manifold assume that a symmetric (0,2)-tensor field $h = \pounds_{\xi}g + 2S + 2\mu\eta \otimes \eta$ is parallel with respect to the Levi-Civita connection associated to g. Then (g, ξ) yields a conformal η -Einstein soliton.

Proof. Note that h is a symmetric tensor field of (0,2)-type, which we suppose to be parallel with respect to the Levi-Civita connection ∇ , i.e $\nabla h = 0$. Applying the Ricci commutation identity, we have

$$\nabla^2 h(X,Y;Z,W) - \nabla^2 h(X,Y;W,Z) = 0$$

for all vector fields *X*, *Y*, *Z*, *W* on *M*. From the above equation we obtain the relation

$$h(R(X,Y)Z,W) + h(Z,R(X,Y)W) = 0.$$

Replacing $Z = W = \xi$ in the above equation and using (7), we get

$$\eta(X)h(Y,\xi) - \eta(Y)h(X,\xi) = 0.$$

Replacing $X = \xi$ and using (3), the above equation reduces to

$$h(Y,\xi) = \eta(Y)h(\xi,\xi) \tag{23}$$

for all vector fields Y on M. Differentiating the above equation covariantly with respect to X, we get

$$\nabla_X(h(Y,\xi)) = \nabla_X(\eta(Y)h(\xi,\xi)).$$

Now expanding the above eqution by using (23), (6), (9) and the property $\nabla h = 0$, we obtain

$$h(X,Y) = h(\xi,\xi)g(X,Y) \tag{24}$$

for all vector fields *X*, *Y* on *M*.

Let us take

$$h = \pounds_{\xi} g + 2S + 2\mu \eta \otimes \eta. \tag{25}$$

Then from (11), (12), we get

$$h(\xi,\xi) = -2\lambda - \left(p + \frac{2}{2n+1}\right) + r.$$

Then using (25), equation (24) becomes

$$(\pounds_{\xi}g)(X,Y) + 2S(X,Y) + \left[2\lambda - r + \left(p + \frac{2}{2n+1}\right)\right]g(X,Y) + 2\mu\eta(X)\eta(Y) = 0,$$

which is the conformal η -Einstein soliton. Hence, we complete the proof.

Definition 2. A Kenmotsu manifold is said to be Ricci-recurrent manifold if there exists a non-zero 1-form A such that

$$(\nabla_W S)(Y, Z) = A(W)S(Y, Z) \tag{26}$$

for any vector fields W, Y, Z on M.

Theorem 7. If the metric of a (2n+1)-dimensional Ricci-recurrent Kenmotsu manifold is a conformal η -Einstein soliton with the 1-form A, then the scalar curvature becomes

$$2\lambda + 2\mu + \left(p + \frac{2}{2n+1}\right) + 4n(A(\xi) - 1).$$

Proof. Replacing Z by ξ in the equation (26) and using (8), we get

$$(\nabla_W S)(Y, \xi) = -2nA(W)\eta(Y)$$

which implies that

$$WS(Y,\xi) - S(\nabla_W Y,\xi) - S(Y,\nabla_W \xi) = -2nA(W)\eta(Y).$$

Using (8) and (6), the above equation becomes

$$2n(\nabla_W \eta)Y + 2n\eta(W)\eta(Y) + S(Y,W) = 2nA(W)\eta(Y).$$

Again using (9), the above equation reduces to

$$2ng(W,Y) + S(Y,W) = 2nA(W)\eta(Y).$$

Taking $W = \xi$ in the above equation and using (12), we obtain

$$r = 2\lambda + 2\mu + \left(p + \frac{2}{2n+1}\right) + 4n(A(\xi) - 1).$$

This completes the proof.

Example 1. Here, we consider the three-dimensional manifold $M = \{(x, y, z) \in \mathbb{R}^3, (x, y, z) \neq (0, 0, 0)\}$, where (x, y, z) are standard coordinates in \mathbb{R}^3 . The vector fields

$$e_1 = z \frac{\partial}{\partial x}$$
, $e_2 = z \frac{\partial}{\partial y}$, $e_3 = -z \frac{\partial}{\partial z}$

are linearly independent at each point of M. Let g be the Riemannian metric defined by

$$g(e_1, e_2) = g(e_2, e_3) = g(e_3, e_1) = 0,$$
 $g(e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1.$

Let η be the 1-form defined by $\eta(Z) = g(Z, e_3)$ for any vector field Z in \mathbb{R}^3 and ϕ be the (1,1)-tensor field defined by $\phi e_1 = -e_2$, $\phi e_2 = e_1$, $\phi e_3 = 0$. Then using the linearity of ϕ and g, we have

$$\eta(e_3) = 1$$
, $\phi^2 Z = -Z + \eta(Z)e_3$, $g(\phi Z, \phi W) = g(Z, W) - \eta(Z)\eta(W)$

for any $Z, W \in \chi(M)$. Thus for $e_3 = \xi$, (ϕ, ξ, η, g) defines an almost contact metric structure on M.

Let ∇ be the Levi-Civita connection with respect to the Riemannian metric g. Then we have $[e_1, e_2] = 0$, $[e_1, e_3] = e_1$, $[e_2, e_3] = e_2$. The connection ∇ of the metric g is given by

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]),$$

which is known as Koszul's formula.

Using Koszul's formula, we can easily calculate

$$abla_{e_1}e_1 = -e_3, \quad
abla_{e_1}e_2 = 0, \quad
abla_{e_1}e_3 = e_1, \\

abla_{e_2}e_1 = 0, \quad
abla_{e_2}e_2 = -e_3, \quad
abla_{e_2}e_3 = e_2, \\

abla_{e_3}e_1 = 0, \quad
abla_{e_3}e_2 = 0, \quad
abla_{e_3}e_3 = 0.$$

From the above it follows that the manifold satisfies $\nabla_X \xi = X - \eta(X)\xi$ for $\xi = e_3$. Hence the manifold is a Kenmotsu manifold. So, here we have considered \mathbb{R}^3 as an almost contact manifold, which turns out to be a 3-dimensional Kenmotsu manifold.

Also, the Riemannian curvature tensor R is given by

$$R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z.$$

Hence,

$$R(e_1, e_2)e_2 = -e_1$$
, $R(e_1, e_3)e_3 = -e_1$, $R(e_2, e_1)e_1 = -e_2$, $R(e_2, e_3)e_3 = -e_2$, $R(e_3, e_1)e_1 = -e_3$, $R(e_3, e_2)e_2 = -e_3$, $R(e_1, e_2)e_3 = 0$, $R(e_2, e_3)e_1 = 0$, $R(e_3, e_1)e_2 = 0$.

Then, the Ricci tensor *S* is given by $S(e_1, e_1) = -2$, $S(e_2, e_2) = -2$, $S(e_3, e_3) = -2$. From (12), we have

$$S(e_3, e_3) = -\left[\lambda + \mu - \frac{r}{2} + \frac{\left(p + \frac{2}{3}\right)}{2}\right],$$

which implies that

$$r = 2\lambda + 2\mu - 4 + \left(p + \frac{2}{3}\right).$$

Hence λ and μ satisfies equation (13) and so g defines a conformal η -Einstein soliton on the 3-dimensional Kenmotsu manifold M.

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Метою даної роботи є вивчення деяких властивостей многовида Кенмоцу, метрика якого є конформним η -солітоном Айнштайна. Ми дослідили певні властивості многовида Кенмоцу, що допускає конформний η -солітон Айнштайна. Також ми збудували тривимірний многовид Кенмоцу, що задовольняє конформний η -солітон Айнштайна.

Ключові слова і фрази: солітон Айнштайна, η -солітон Айнштайна, конформний η -солітон Айнштайна, η -многовид Айнштайна, многовид Кенмоцу.